CHAPTER 1 :

I. Physical Quantities and Dimensional Analysis

The comprehension of physical phenomena remains incomplete without the acquisition of quantitative information, which essentially involves measuring physical quantities. In the exploration of a physical phenomenon, a thorough investigation of significant variables is imperative. The mathematical interrelation among these variables gives rise to a physical law. While such relationships can be established in certain instances, there are situations where a modeling approach becomes essential, such as in the case of dimensional analysis. This method proves invaluable when dealing with complex or less understood phenomena, enabling a systematic and insightful exploration of their underlying principles.

I.1-Physical Quantities

Physical quantities are classified according to two categories: base quantities and derived

quantities

- \triangleright Base quantities: they are self-defined quantities such as length, mass, time etc,
- \triangleright Derived quantities: they are quantities that are derived from basic quantities and are

known by their meanings, such as speed, acceleration, force, and pressure etc.

I. 2- The International System of Units (SI system)

Specific and uniform standards must be used across the world; quantities determine dimensions and dimensions are estimated in units. The international system of units SI or MKSA system consists of 7 base units adapted to 7 physical quantities, as shown in the following table:

Table I.1: The international system of units (SI system)

I. 3- Dimensional Analysis

It is a theoretical tool for interpreting problems based on the dimensions of the physical

quantities involved: length, time, mass, etc. Dimensional analysis makes it possible to:

- \triangleright Check the validity of equations with dimensions
- \triangleright Research into the nature of physical quantities
- \triangleright Search for the homogeneity of physical laws
- \triangleright Determine the unit of a physical quantity based on the essential units (meter, second,kilogram, etc.)

The dimensional equation is represented by the following writing:

$\mathbf{[X]} = \mathbf{M}^{\mathbf{a}} \mathbf{L}^{\mathbf{b}} \mathbf{T}^{\mathbf{c}} \mathbf{I}^{\mathbf{d}} \mathbf{\theta}^{\mathbf{e}} \mathbf{N}^{\mathbf{f}} \mathbf{J}^{\mathbf{j}}$

Where

M^a : Mass (Kg)

 L^b **:** Length (m)

 T^c :Time (s)

I d :Electric current intensity (A)

θ e :Temperature (K)

N f :Mole (mol)

J j : Light intensity (cd)

Where

[π]=1 , []=1 , [t]=T , [m] =M , [l]=L , [i]=I

Some quantities have no dimensions

Example

The dimensional equation of

Linear speed:

$$
V = \frac{d}{t} \Rightarrow [V] = \left[\frac{d}{t}\right] = \frac{[d]}{[t]} = \frac{L}{T} = L.T^{-1}
$$
unit of (V) SI : m.s⁻¹

Acceleration:

$$
a = \frac{v}{d} \Rightarrow [\gamma] = \left[\frac{v}{t}\right] = \frac{[v]}{[t]} = \frac{L \cdot T^{-1}}{T} = L \cdot T^{-2}
$$

unit of (a) $SI : m.s^{-2}$

Force:

$$
F=m.a \implies [F] = [m.a]=[m].[a] = M.L.T^{-2}
$$

unit of (F) SI :N

Work :

 $W = F.d \implies [W] = [F.d] = [F] . [d] = M.L.T^{-2}.L$ $[W] = M L^2 T^{-2}$

unit of (W) SI :J

Pressure :

$$
P = \frac{F}{s} \Rightarrow [P] = \left[\frac{F}{s}\right] = \frac{[F]}{[s]} = \frac{M.L.T^{-2}}{L^2} = M.L^{-1}.T^{-2}
$$

unit of (P) SI :Pa

I. 4- Dimensional Uniformity

Dimensional equations are used to verify the homogeneity of formulas :

For example, Ec= $\frac{1}{2}$ m.v² is homogeneous to an energy (i.e., work). The dimensional equation for work is t W = ML²T ⁻²et $[Ec] = [\frac{1}{2} \text{ m. } v^2] = [\frac{1}{2} \cdot [m] \cdot [v]^2 = M \cdot L^2 \cdot T^{-2}$

Note :

Addition, subtraction, as well as inequality or comparison, must be done between terms of the same dimension, i.e., homogenous terms.

Any non-homogeneous result is necessarily false.

Example:

Verify the homogeneity of the following equation:

$$
x = \frac{1}{2} a t^2 + v_0 t
$$

\n
$$
[x] = [\frac{1}{2}, a.t^2 + v_0 t] \Rightarrow [x] = [\frac{1}{2}, a.t^2] + [v_0 t] \Rightarrow [x] = [\frac{1}{2}].[a].[t^2] + [v_0].[t]
$$

\n
$$
\Rightarrow L = 1. LT^{-2}.T^2 + LT^{-1}.T^1
$$

 \Rightarrow L = L So the equation is homogeneous.

II.Calculation of Error

In experimental science, there is no exact measurement. Measurements are subject to more or less significant errors depending on the quality of the instruments and the skill of the experimenter.

• A discrepancy exists between the obtained value and the exact value, which remains unknown.

- This discrepancy is referred to as "measurement error."
- The true value remaining unknown.
- The measurement error will remain undetermined.

The absolute error and the relative error:

In practice, errors can only be estimated there are two types of errors:

The absolute error

The absolute error represents the mathematical quantity that measures the difference between the measured or observed value of a quantity and its true or theoretical value. It is calculated by taking the absolute value of the difference between these two values. The general formula for absolute error (E_{abs}) is as follows:

$E_{\rm abs} = |{\rm Measured\ value} - {\rm True\ value}|$

This measure allows the assessment of the overall discrepancy between the experimental measurement and the expected value, irrespective of the direction of this difference. The absolute error is a crucial tool in the analysis of experimental results and helps quantify the accuracy of the measurements taken.

the relative error

I provided the general formula for relative error in the previous response. If you have specific values for the approximate value and true value, you can plug them into the formula to calculate the relative error.

To reiterate:

$$
RE = \frac{|\text{Approximate Value} - \text{True Value}|}{|\text{True Value}|}
$$

And if you want the result as a percentage:

$$
\text{Relative Error } (\%) = \left(\frac{|\text{Approximate Value} - \text{True Value}|}{|\text{True Value}|}\right) \times 100\%
$$

If you provide the specific values you're working with, I can help you calculate the relative error.

Uncertainty calculations

For a quantity $g=f(x,y,z)$, its total differential is expressed as:

$$
dg = \frac{\partial g}{\partial x}dx + \frac{\partial g}{\partial y}dy + \frac{\partial g}{\partial z}dz
$$

The absolute uncertainty on the variable g is obtained by considering the variations in the variables that compose it, namely:

$$
\Delta g = \left| \frac{\partial g}{\partial x} \right| \Delta x + \left| \frac{\partial g}{\partial y} \right| \Delta y + \left| \frac{\partial g}{\partial z} \right| \Delta z
$$