Incrtain decesion

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Marchov chains

- A Markov chain describes a system whose state changes over time.
- The changes are not completely predictable, but rather are governed by probability distributions.

- The future of the system depends only to its present state, and not the path by which the system got to this latter.

I. Marchov chains

Definitions 1

A time-homogeneous Markov chain is a discretetime stochastic process $(X_n, n \ge 0)$ with values in a finite or countable set S (the state space) such that:

 $P(X_{n+1} = j | X_n = i, X_{n-1} = i_{n-1}, X_{n-2} = i_{n-2}, \ldots, X_0 = i_0) = P(X_{n+1} = j | X_n = i) = P_{ij}$ for every $n \ge 0$ and j, i, i_{n-1} , ..., i_1 , $i_0 \in S$.

I. Marchov chains

The **transition matrix** of the chain is the matrix $P = (p_{ii})$ i,j∈S defined as $p_{ii} = P(X_{n+1} = j | X_n = i)$. It satisfies the following properties: $0 \le p_{ii} \le 1 \forall i, j \in S$ and $\Sigma_{i \in S} p_{ij} = \Sigma_{i \in S} P(X_{n+1} = j | X_n)$ $= i$) = 1 $\forall i \in S$

Note however that for a given $j \in S$, $\Sigma_{i \in S}$ p $_{ii}$ can be anything.

I. Markov chains

The transition graph of the chain is the oriented graph where vertices are states and an arrow from i to j exists if and only if $p_{ii} > 0$, taking value p_{ii} when it exists.

II. Distribution

The distribution of the Markov chain at time $n \geq 0$ is given by:

$$
\pi_i^{(n)} = P(X_n = i) i \in S
$$

and its initial distribution is given by

$$
\pi_i^{(0)} = P(X_0 = i) i \in S
$$

For every $n \geq 0$, we have

$$
\Sigma_{i\in S}\pi_i^{(n)}=1
$$

II Distribution

The main question that will retain our attention for the first part of the course:

When does $\pi^{(n)}$ (the distribution at time n) converge at n $\rightarrow \infty$ to some limiting distribution π ?

Definition 2. we define m-step transition probabilities, for $m \geq 1$ and i, $j \in S$,

$$
p_{ij^{(m)}} = P(X_{n+m} = j | X_n = i) = P(X_m = j | X_0 = i)
$$

How to compute these probabilities? Using the Chapman-Kolmogorov equations.

For
$$
m = 2
$$
, these lead.

$$
p_{ij}^2 = \sum_{k \in S} p_{ik} p_{kj} = (P \cdot P)_{ij} = (P 2)_{ij}
$$

Indeed, we check that :

$$
p_{ij}^{(2)} = P(X_2 = j | X_0 = i) = \sum_{k \in S} P(X_2 = j, X_1 = k | X_0 = i)
$$

= $\sum_{k \in S} P(X_2 = j | X_1 = k, X_0 = i)^* p(X_1 = k | X_0 = i)$

 $=\sum_{k\in S}p_{ki}^{*}p_{ik}$

For higher values of m and $0 \le l \le m$, Chapman-Kolmogorov equations read:

$$
p_{ij}^{(m)} = \sum_{k \in S} p_{ik}^{(l)} p_{kj}^{(m-l)} = (P^{(l)} \cdot P^{(m-l)}) ij = (P^m)_{ij}
$$

\n
$$
p_{ij}^{(m)} = P[X_m = j/X_0 = i] = \sum_{k \in S} P[X_m = j, X_i = k/X_0 = i] = \sum_{k \in S} P[X_m = j / X_i = k, X_0 = i] * P[X_i = k / X_0 = i]
$$

\n
$$
= \sum_{k \in S} p_{ik}^{(l)} p_{kj}^{(m-l)}.
$$

Example 1

Consider a Markov chain given in previous section. Determine P[X_3 =F / X_0 =S] and P[X_5 =R / X_2 =F].

IV Classification of states

Definitions 3.

Two states i, j \in S communicate ("i \leftarrow + j") if $\exists n$, m ≥ 0 such that $p_{ij}^{(n)} > 0$ and $p_{ij}^{(m)} > 0$.

A chain is said to be irreducible if all states communicate (a single class).

A state i is said to be absorbing if $p_{ii} = 1$.

IV Classification of states

Definitions 4.

Periodicity. For a state $i \in S$, define $d_i = \gcd(\{n \ge 1 :$ p_{ii} ⁿ > 0}). If $d_i = 1$, we say that state i is aperiodic. Else if $d_i > 1$, we say that state i is periodic with period d_i .

- In a given class, all states have the same period $d_i = d$.

- If there is at least on self-loop in the class ($\exists i \in S$ such as $p_{ii} > 0$), then all states in the class are aperiodic.

IV Classification of states

Definition 5

A state i \in S is recurrent if $f_{ii} = P(\exists n \ge 1 \text{ such that } X_n = i$ $X_0 = i = 1$

(i.e., the probability that the chain returns to state i in finite time is equal to 1).

- A state i \in S is transient if f_{ii} < 1.

So a state is recurrent if and only if it is not transient.

Note in particular that it is not necessary that $f_{ii}=0$ for state i to be transient.

states 1, 2 and 3 are transient and 4 is recurrent.

IVClassification of states

- In a given class, either all states are recurrent, or all states are transient.

- In a finite chain, a class is recurrent iff there is no arrow leading out of it. (So a finite irreducible chain is always recurrent.)

V Stationary distribution

As a reminder, the distribution of the Markov chain $(X_n, n \ge 0)$ at time n is given by: $\pi_j^{(n)} = P(X_n = j), j \in S$: Let us compute for $j \in S$: $\pi_j^{(n+1)} = P(X_{n+1} = j) = \sum_{i \in S} P(X_{n+1} = j, X_n = i)$ $=\sum_{i \in S} P(X_{n+1} = j / X_n = i) P(X_n = i) = \sum_{i \in S} \pi_i^{(n)} p_{ij}$

V Stationary distribution

In vector notation (considering $\pi^{(n)}$, $\pi^{(n+1)}$ as row vectors), this reads: $π(n+1) = π(n)$ P

which further implies that $\pi^{(n)} = \pi^{(0)}$ P_n. This motivates also the following definition:

Let $(X_n, n \ge 0)$ be a Markov chain with transition matrix P

A probability distribution $\pi = (\pi_{i}, i \in S)$ is said to be a stationary distribution of the chain X if:

 $\pi_i = \Sigma_i \in S \pi_i p_{ii}$ $\forall j \in S$ i.e. $\pi = \pi P$.

VI Ergodic Markov chain

Definition 6

A Markov chain is said to be ergodic if it is irreducible, aperiodic and recurrent.

Theorem (Ergodic theorem). Let X be an ergodic Markov chain. Then it admits a unique limiting and stationary distribution π , i.e., $\nabla \pi$ (0), $\lim_{n\to\infty} \pi$ (n) = π and $\pi = \pi P$.

VII Stationary distribution

If π is stationary then $\pi P^n = \pi P P^{n-1} = \pi P^{n-1} = ... = \pi$.

• In particular, if the initial distribution π (0) = π , then $\forall n$ ≥ 0 , π (n) = π 0) P n = πPn = π.

Remarks

we can see than $π$ is a (left-)eigenvector of P .

Stationary distribution

The stationary distribution of the Markov chain previously mentioned is

 $\Pi = [\frac{1}{4}, \frac{1}{2}, \frac{1}{4}]$.