

Deep learning

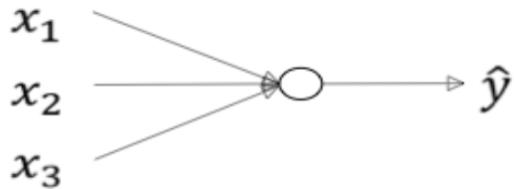
Dr. Aissa Boulmerka
a.boulmerka@centre-univ-mila.dz

2023-2024

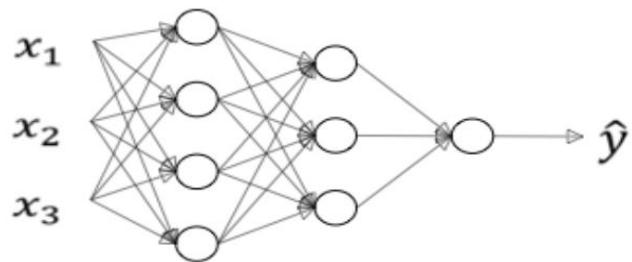
CHAPTER 3

DEEP NEURAL NETWORKS

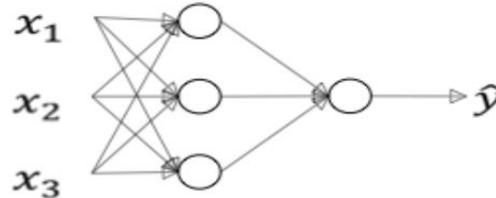
What is a deep neural network?



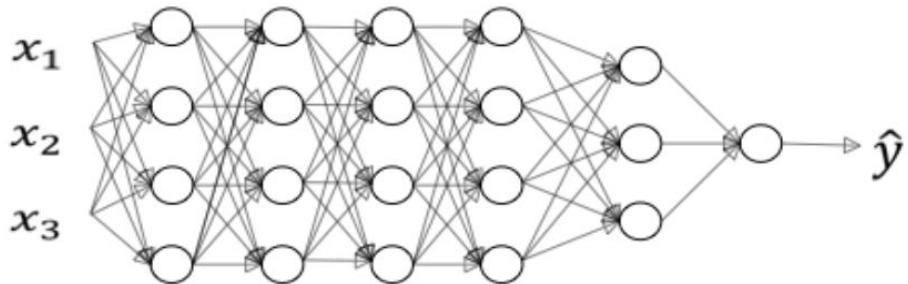
logistic regression
Shallow



2 hidden layers
3 layer NN

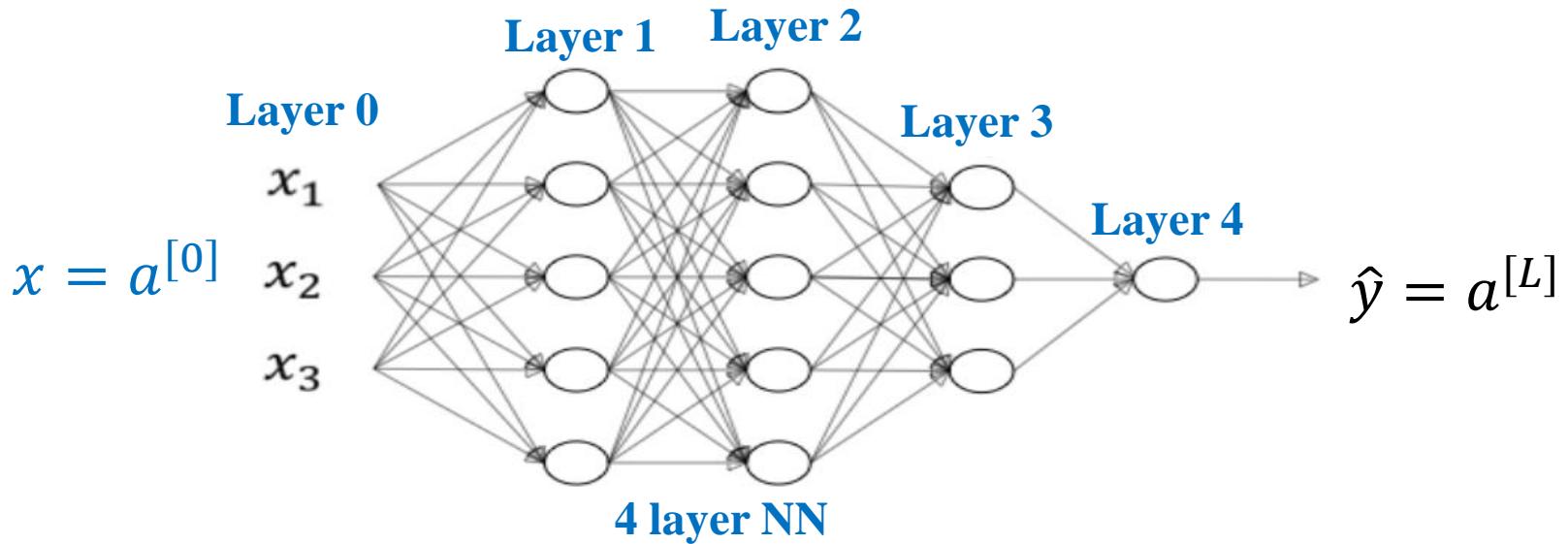


1 hidden layer
2 layer NN



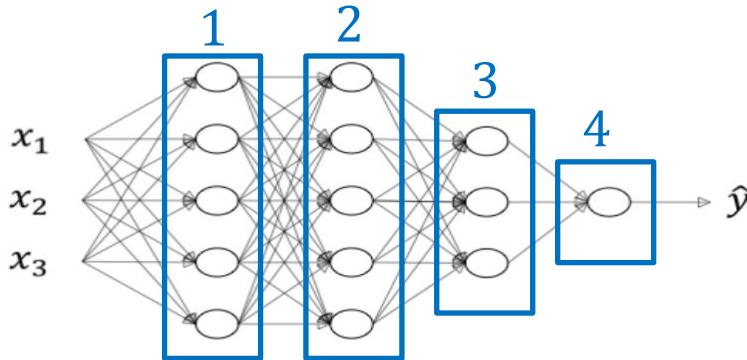
5 hidden layers
Deep

Deep neural network notation



- $n^{[0]} = n_x = 3, n^{[1]} = 5, n^{[2]} = 5, n^{[3]} = 3, n^{[4]} = n^{[l]} = 1$
- $L = 4$: number of layers
- $n^{[l]}$: number of units in layer l
- $a^{[l]}$: activations in layer l with $a^{[l]} = g^{[l]}(z^{[l]})$
- $W^{[l]}, b^{[l]}$: weights for $z^{[l]}$

Forward propagation in a deep network

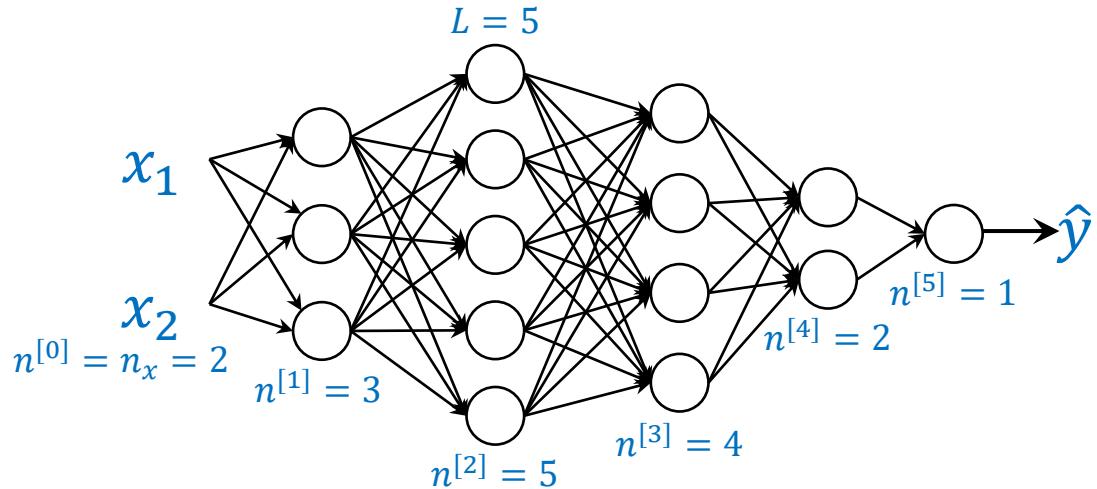


$$A^{[0]} = X$$
$$Z^{[l]} = W^{[l]}A^{[l-1]} + b^{[l]}$$
$$A^{[l]} = g^{[l]}(Z^{[l]})$$

Iterative	Vectorized
$z^{[1]} = W^{[1]}a^{[0]} + b^{[1]}$	$Z^{[1]} = W^{[1]}A^{[0]} + b^{[1]}$
$a^{[1]} = g^{[1]}(z^{[1]})$	$A^{[1]} = g^{[1]}(Z^{[1]})$
$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$	$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$
$a^{[2]} = g^{[2]}(z^{[2]})$	$A^{[2]} = g^{[2]}(Z^{[2]})$
\vdots	\vdots
$z^{[4]} = W^{[4]}a^{[3]} + b^{[4]}$	$Z^{[4]} = W^{[4]}A^{[3]} + b^{[4]}$
$\hat{y} = a^{[4]} = g^{[4]}(z^{[4]})$	$\hat{Y} = A^{[4]} = g^{[4]}(Z^{[4]})$

Getting your matrix dimensions right

Parameters $W^{[l]}$ and $b^{[l]}$



- $W^{[l]}: (n^{[l]}, n^{[l-1]})$
- $b^{[l]}: (n^{[l]}, 1)$
- $dW^{[l]}: (n^{[l]}, n^{[l-1]})$
- $db^{[l]}: (n^{[l]}, 1)$
- $z^{[l]}: (n^{[l]}, 1)$
- $a^{[l]} = g^{[l]}(z^{[l]}): (n^{[l]}, 1)$

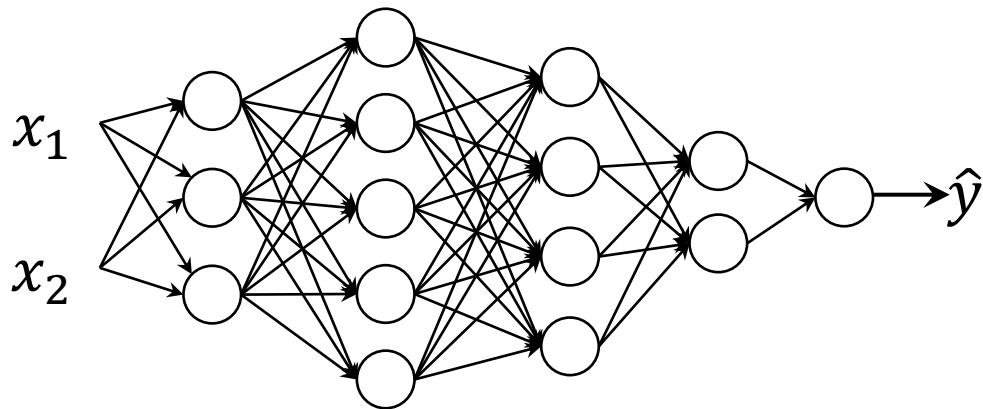
$$z^{[1]} = W^{[1]}x + b^{[1]}$$

$$\begin{matrix} (3,1) & (3,2) & (2,1) & (3,1) \\ (n^{[1]}, 1) & (n^{[1]}, n^{[0]}) & (n^{[0]}, 1) & (n^{[1]}, 1) \end{matrix}$$

$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

$$\begin{matrix} (5,1) & (5,3) & (3,1) & (5,1) \\ (n^{[2]}, 1) & (n^{[2]}, n^{[1]}) & (n^{[1]}, 1) & (n^{[2]}, 1) \end{matrix}$$

Vectorized implementation



$$z^{[1]} = W^{[1]}x + b^{[1]}$$

$$(n^{[1]}, 1) \quad (n^{[1]}, n^{[0]})(n^{[0]}, 1) \quad (n^{[1]}, 1)$$

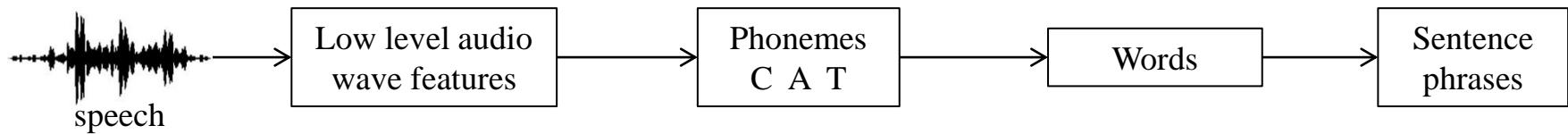
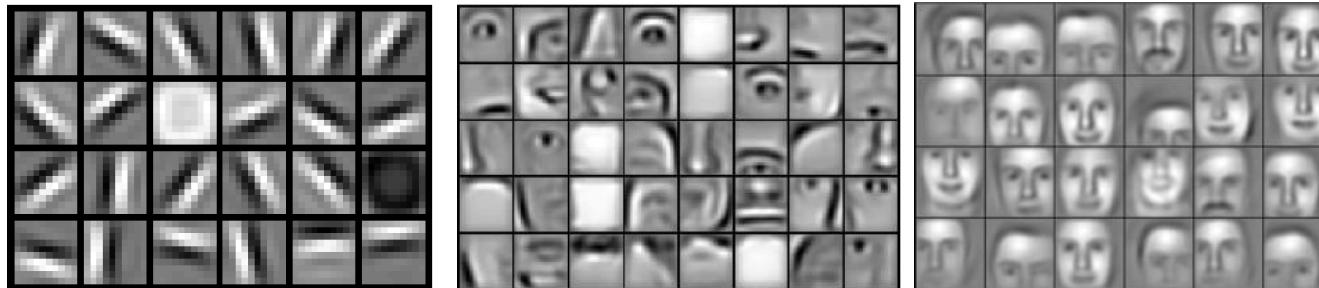
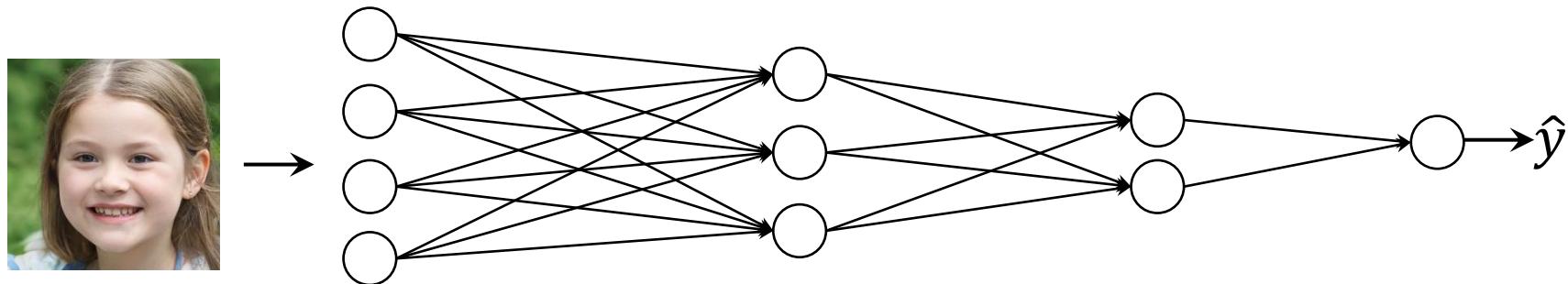
$$Z^{[1]} = W^{[1]}X + b^{[1]}$$

$$(n^{[1]}, m) \quad (n^{[1]}, n^{[0]}) (n^{[0]}, m) \quad (n^{[1]}, 1)$$

$\rightarrow (n^{[1]}, m)$ broadcasting

- $z^{[l]}, a^{[l]}: (n^{[l]}, 1)$
 - $dz^{[l]}, da^{[l]}: (n^{[l]}, 1)$
 - $Z^{[l]}, A^{[l]}: (n^{[l]}, m)$
 - $l = 0: A^{[0]}: (n^{[0]}, m)$
 - $dZ^{[l]}, dA^{[l]}: (n^{[l]}, m)$

Intuition about deep representation

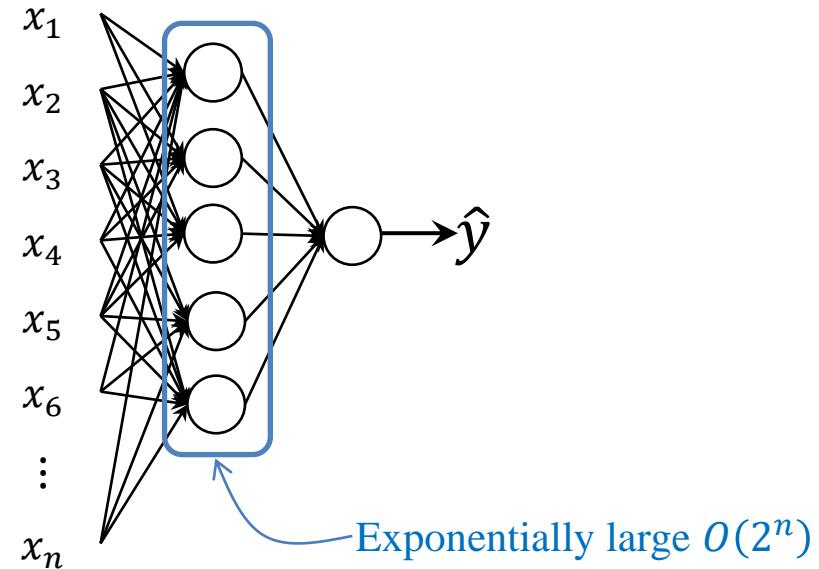
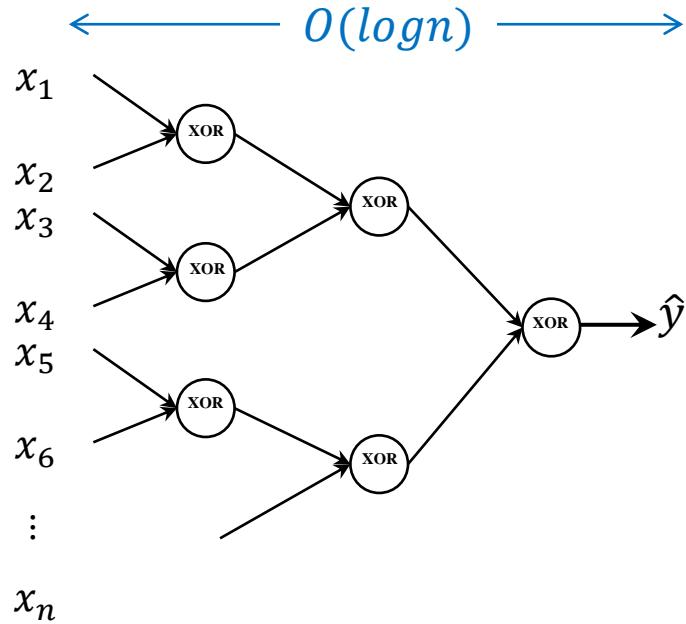


(*) Note that the image in the above example is generated by the algorithm from : <https://this-person-does-not-exist.com>

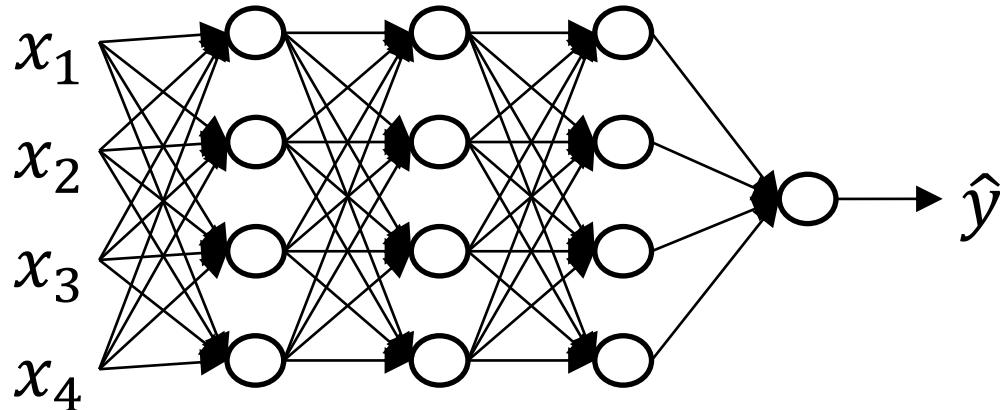
Circuit theory and deep learning

Informally: There are functions you can compute with a “small” L-layer deep neural network that shallower networks require exponentially more hidden units to compute.

$$y = x_1 \text{XOR} x_2 \text{XOR} x_3 \text{XOR} \cdots \text{XOR} x_n$$



Forward and backward functions



Layer l : $W^{[l]}, b^{[l]}$

- **Forward:**

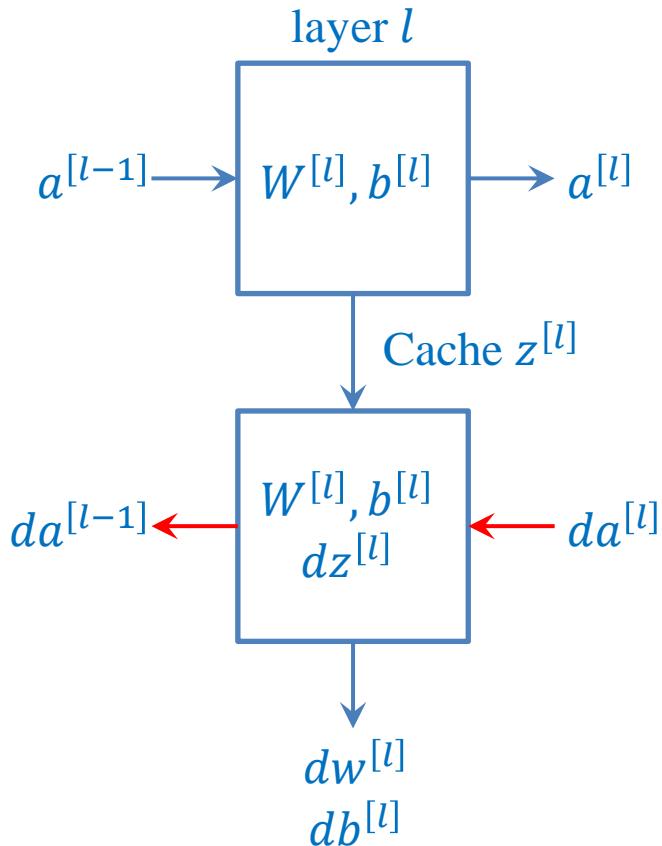
Input $a^{[l-1]}$, output: $a^{[l]}$

$$z^{[l]} = W^{[l]}a^{[l-1]} + b^{[l]} \quad (\text{Cache } z^{[l]})$$
$$a^{[l]} = g^{[l]}(z^{[l]})$$

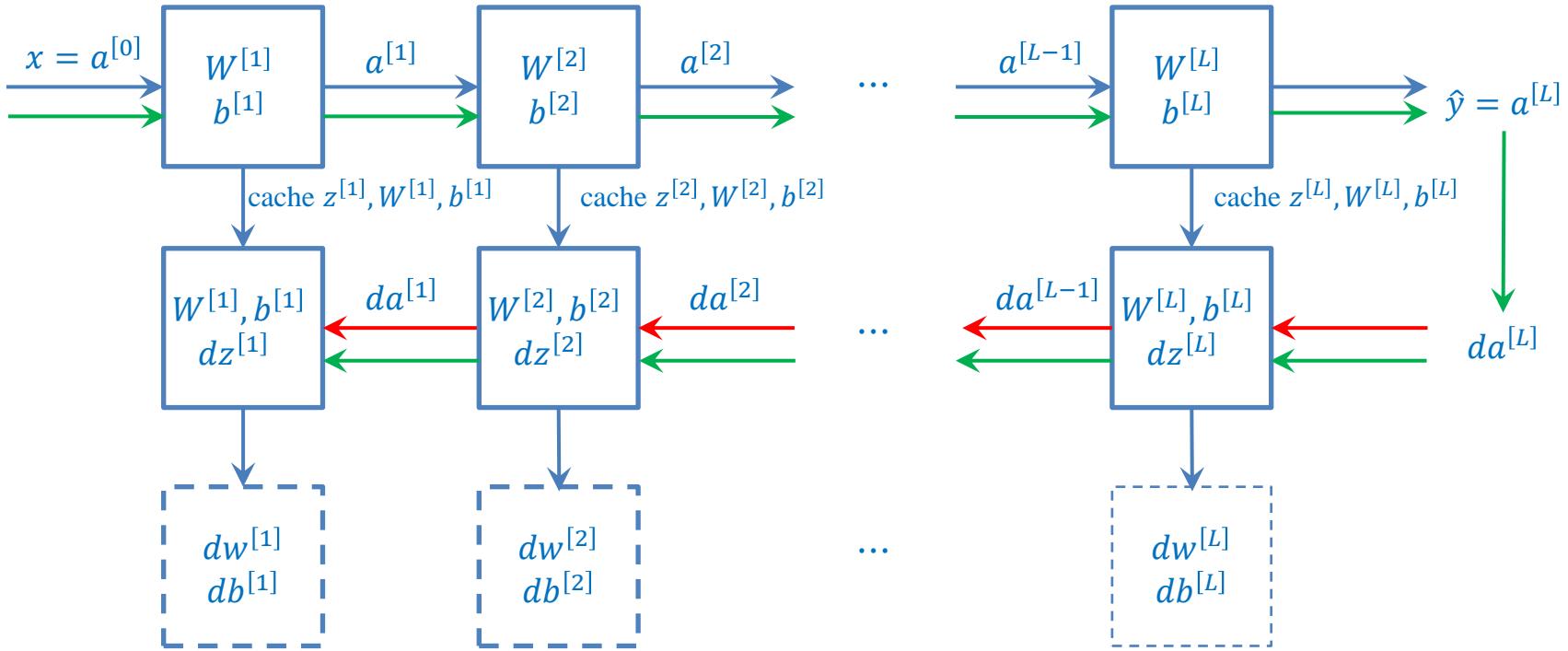
- **Backward:**

Input: $da^{[l]}$, cache ($z^{[l]}$)

Output: $da^{[l-1]}, dw^{[l]}, db^{[l]}$



Forward and backward functions



$$\begin{aligned} W^{[l]} &\leftarrow W^{[l]} - \alpha dw^{[l]} \\ b^{[l]} &\leftarrow b^{[l]} - \alpha db^{[l]} \end{aligned}$$

Forward propagation for layer l

Input: $a^{[l-1]}$

Output: $a^{[l]}, \text{Cache}(Z^{[l]})$

Vectorized:

$$\begin{aligned} z^{[l]} &= W^{[l]}a^{[l-1]} + b^{[l]} \\ a^{[l]} &= g^{[l]}(z^{[l]}) \end{aligned}$$

$$\begin{aligned} Z^{[l]} &= W^{[l]}A^{[l-1]} + b^{[l]} \\ A^{[l]} &= g^{[l]}(Z^{[l]}) \end{aligned}$$

Backward propagation for layer l

Input: $da^{[l]}$

Output: $da^{[l-1]}, dW^{[l]}, db^{[l]}$

$$dz^{[l]} = da^{[l]} * g^{[l]'}(z^{[l]})$$

$$dW^{[l]} = dz^{[l]} \cdot a^{[l-1]}$$

$$db^{[l]} = dz^{[l]}$$

$$da^{[l-1]} = W^{[l]T} \cdot dz^{[l]}$$

If we *substitute* $da^{[l]}$ to $dz^{[l]}$:

$$dz^{[l]} = W^{[l+1]T} dz^{[l+1]} * g^{[l]'}(z^{[l]})$$

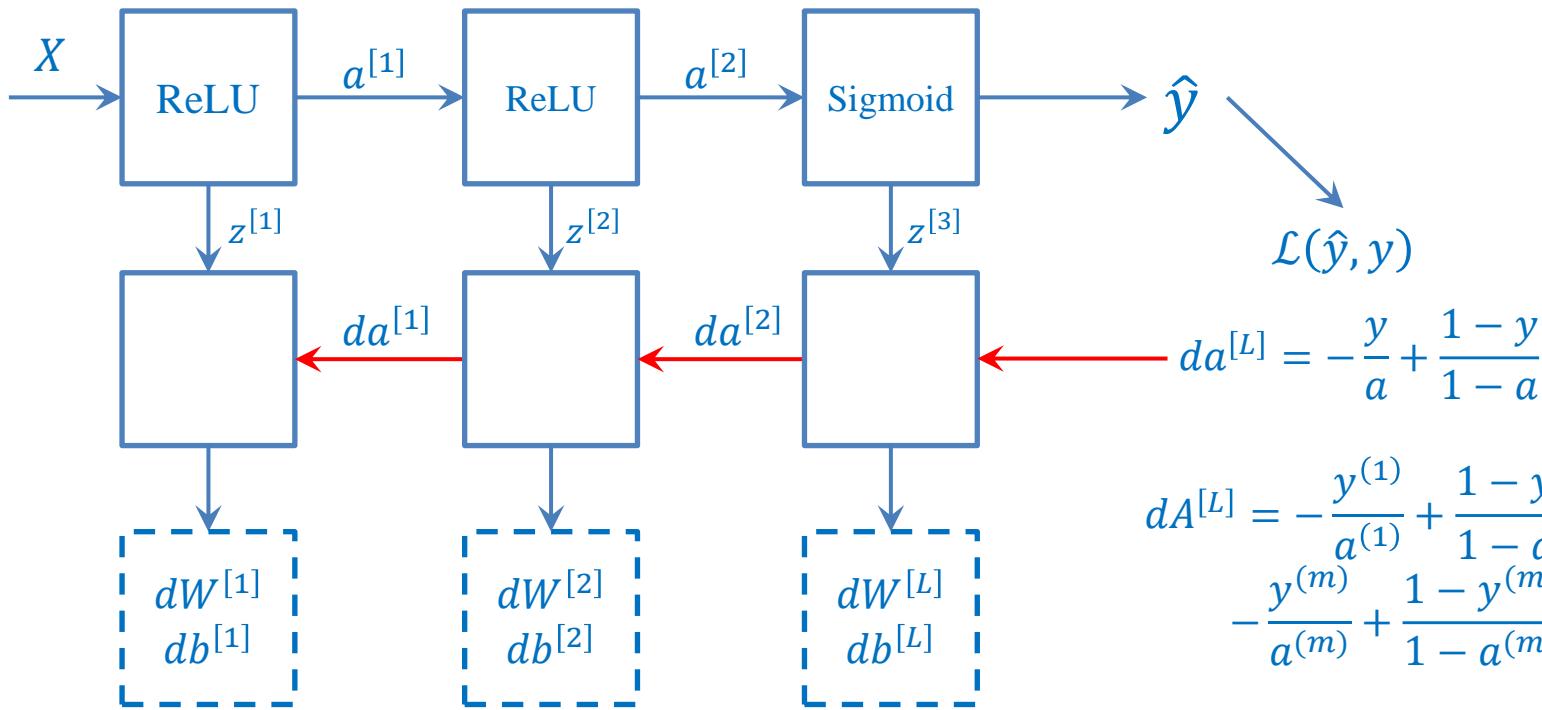
$$dZ^{[l]} = dA^{[l]} * g^{[l]'}(Z^{[l]})$$

$$dW^{[l]} = \frac{1}{m} dZ^{[l]} \cdot A^{[l-1]T}$$

$$db^{[l]} = \frac{1}{m} \text{np.sum}(dZ^{[l]}, \text{axis}=1, \text{keepdims}=\text{True})$$

$$dA^{[l-1]} = W^{[l]T} \cdot dZ^{[l]}$$

Summary

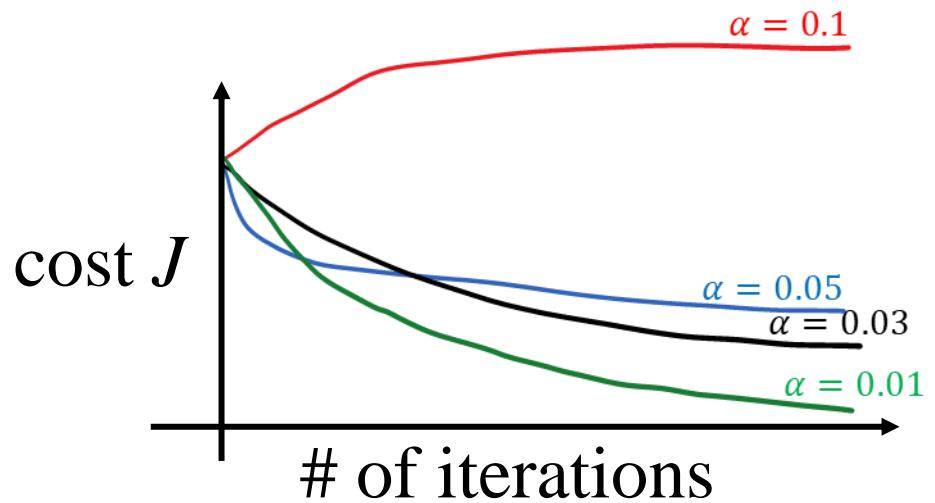
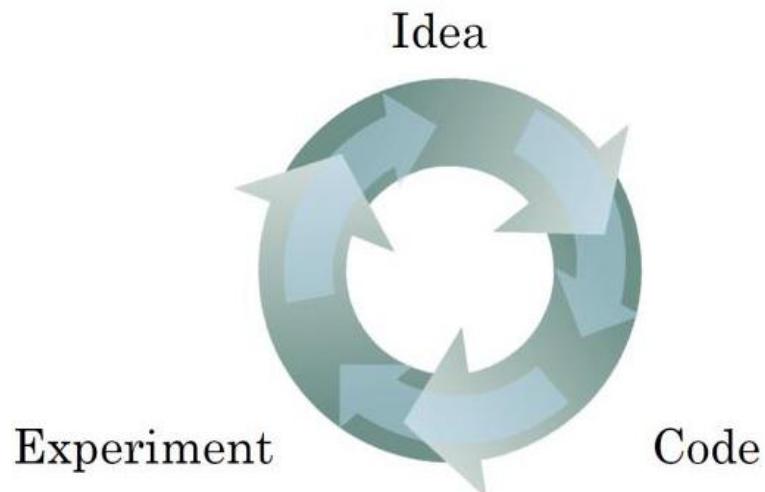


Parameters vs Hyperparameters

- **Parameters:** $W^{[1]}, b^{[1]}, W^{[2]}, b^{[2]}, W^{[3]}, b^{[3]}, \dots$
- **Hyperparameters:**
 - Learning rate: α
 - Number of iterations
 - Number of hidden layers: L
 - Number of hidden units: $n^{[1]}, n^{[2]}, n^{[3]}, \dots, n^{[L]}$
 - Choice of activation function

Later: descent gradient optimization method, momentum, mini-batch size, regularization, ... etc.

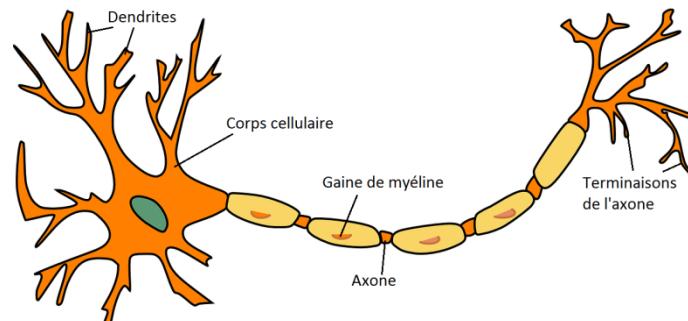
Parameters: Applied deep learning is a very empirical process



What does this have to do with the brain?

- Forward and backward propagation:

Forward propagation	Backward propagation
$Z^{[1]} = W^{[1]}X + b^{[1]}$	$dZ^{[L]} = A^{[L]} - Y$
$A^{[1]} = g^{[1]}(Z^{[1]})$	$dW^{[L]} = \frac{1}{m} dZ^{[L]} A^{[L]T}$
$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$	$db^{[L]} = \frac{1}{m} np.sum(dZ^{[L]}, axis = 1, keepdims = True)$
$A^{[2]} = g^{[2]}(Z^{[2]})$	$dZ^{[L-1]} = dW^{[L]T} dZ^{[L]} g^{[L]'}(Z^{[L-1]})$
\vdots	\vdots
$Z^{[L]} = W^{[L]}A^{[L-1]} + b^{[L]}$	$dZ^{[1]} = dW^{[1]T} dZ^{[2]} g^{[1]'}(Z^{[1]})$
$A^{[L]} = g^{[L]}(Z^{[L]}) = \hat{Y}$	$dW^{[1]} = \frac{1}{m} dZ^{[1]} A^{[1]T}$
	$db^{[1]} = \frac{1}{m} np.sum(dZ^{[1]}, axis = 1, keepdims = True)$



References

- Andrew Ng. Deep learning. Coursera.
- Geoffrey Hinton. Neural Networks for Machine Learning.
- Kevin P. Murphy. Probabilistic Machine Learning An Introduction. MIT Press, 2022.
- MIT Deep Learning 6.S191 (<http://introtodeeplearning.com/>)